# Low Profile Slide Table

### **MXF** Series

### ø8, ø12, ø16, ø20

Low-profile and compact type, air slide table with the construction of guide and cylinder aligned in parallel.

> Low-profile and compactness have been achieved with the construction of guide and cylinder aligned in parallel.

Model	Height x Width (mm)	Height comparison to MXS
MXF8	16 x 58	67%
MXF12	18.5 x 68	59%
MXF16	21 x 80	53%
MXF20	27 x 92	54%

#### Auto switch is mountable

Auto switch is recessed in the

groove to save space.



#### Slim body Low-profile has been achieved

with the construction of guide and cylinder aligned in parallel.

(RoHS)

MXH

MXS

MXO

MXO

MXF

MXW

MXJ MXP MXY

MTS

producibility for mounting and dismounting

Neat appearance

Protecting stopper section

Standard stroke adjustment

Stroke can be adjusted at each

a @

with cover realizes neat

stroke end within 5 mm

each end and 10 mm

appearance.

is total.

Positioning pin holes on table top allows precise and easy mounting to change workpiece

#### Stronger thread for mounting work

Insert thread for mounting work

High rigidity

Body mounting (Body tapped)

Cross roller guide allows smooth

operation without vibration.

#### Reproducibility for mounting

Optional porting

2 directions is possible.

Lateral and axial piping from

and dismounting

Pin holes for positioning on bottom of slide allows precise and accurate mounting of actuator.

Body mounting (Body tapped)

Mounting can be done from 2 directions top side (through-hole) and bottom side (body tapped).

1. Body tapped	2. Body through-hole

#### Series Variations

001100 10	manomo		
Model	Bore size (mm)	Stroke (mm)	Auto switch
		10 20 30 50 75 100	Reed auto switch
MXF8	8	-++++	D-A9□, D-A9□V Solid state auto switch
MXF12	12		D-M9□, D-M9□V
MXF16	16		2-color indicator solid state auto switch
MXF20	20		D-M9□W, D-M9□WV

**SMC** 

D-🗆 -X□

# MXF Series Model Selection

Operating Conditions	Formula/Data	Selection Example
Enumerate the operating conditions considering the mounting position and workpiece configuration. Check that the load weight does not exceed the maximum allowable load weight and that the average operating speed does not exceed the operating speed range. Kinetic Energy	Model to be used     Type of cushion     Workpiece mounting position     Mounting orientation     Average operating speed Va (mm/s)     Load mass W (kg): [#5(1)-Fable(2)     Overhang Ln (mm): [#6(2)]	Cylinder: MXF20-50 Cushion: Rubber bumper Workpiece table mounting Mounting: Horizontal wall mounti Average operating speed: Va = 300 [mm/s] Allowable load: W = 0.5 [kg L1 = 10 mm L3 = 30 mm
Find the kinetic energy E (J)	- 1 V .2	- 1 420 -2
of the load. Find the allowable kinetic energy Ea (J). Confirm that the kinetic energy of the load does not exceed the allowable kinetic energy.	$\begin{split} & E = \frac{1}{2} \cdot W \left( \begin{array}{c} V \\ 1000 \end{array} \right)^2 \\ & Collision \text{ speed } V = \underline{1.4} \cdot Va \text{ *) Correction factor} \\ & (Reference values) \\ & Workpiece \text{ mounting coefficient } K \cdot \underline{FgR(3)} \\ & Max, \text{ allowable kinetic energy (Enay: \underline{Fnb(1)})} \\ & Kinetic energy (E) \leq Allowable kinetic energy (Ea) \end{split}$	$\begin{split} E &= \frac{1}{2} \cdot 0.5 \; (\; \frac{420}{1000} \; )^2 = 0.044 \\ V &= 1.4 \times 300 = 420 \\ \\ Ea &= 1 \cdot 0.16 = 0.16 \\ \\ Can \; be \; used \; based \; on \; E = 0.044 \leq Ea = 0.16 \end{split}$
Load Factor		
Load factor of load mass	W- K 0 W	
Find the allowable load mass Wa (kg). Note) No need to consider this load factor in the case of using perpendicularly in a vertical position (Define $\alpha (1 = 0.)$ Find the load factor of the load mass $\alpha_1$ .	Wa = K-β-Wmax Workpiece mounting coefficient K: Figs(3) Allowable load mass coefficient β: Graph (1) Max. allowable load mass Wmax; Table (2) C/1 = W/Wa	
Load factor of the static mo	ment	
Find the static moment M (N·m). Find the allowable static moment Ma (N·m).	M = W x 9.8 (Ln + An)/1000 Moment center position distance compensation amount An: [Able(3) Ma = K-?/-Mmax Workpiece mounting coefficient K: [Fig.(3) Allowable moment coefficient ?] Maximum allowable moment Mmax: [Able (4)	Yawing         Rolling           Examine My.         Examine Mr.           My = 0.5 × 9.8 (10 + 11)/1000 = 0.11         Mr = 0.5 × 9.8 (30 + 17)/1000 = 0.46 = 17           Aa = 11         A6 = 17           May = 1 × 1 × 9.14 = 9.14         Mar = 9.14 (Same as May)           Mymax = 9.14         K = 1           Y = 1         Y = 1
Find the load factor $\alpha_2$ of the static moment.	Cl2 = M/Ma	$\Omega_{2}^{\prime} = 0.11/9.14 = 0.012$ $\Omega_{2}^{\prime} = 0.23/9.14 = 0.025$
Load factor of dynamic mor	nent	
Find the dynamic moment Me (N-m).	$\begin{split} & Me = 1/3 \cdot We \times 9.8 \ \frac{(Ln + An)}{1000} \\ & Collision equivalent to impact We = \delta \cdot W \cdot V \\ & \delta \cdot Bumper coefficient \\ & With urethane bumper (Standard) = 4/100 \\ & Corrected value for moment \\ & center position distance An: Table(6) \end{split}$	$\label{eq:product} \begin{array}{ c c } \hline Pitching & Examine Mep. \\ \hline Mep = 1/3 \times 8.4 \times 9.8 \times \frac{(30+17)}{1000} = 1.3 \\ \hline We = 4/100 \times 0.5 \times 420 = 8.4 \\ A_2 = 17 \\ \hline Meap = 1 \times 0.7 \times 9.14 = 6.40 \\ \hline K = 1 \\ \hline \gamma = 0.7 \\ \hline Mpmax = 9.14 \end{array}$
Find the allowable dynamic moment Mea (N·m).	Mea = K-Ý-Mmax Workpiece mounting coefficient K: Fig.(3) Allowable moment coefficient ½ Graph (2) Max. allowable moment Mmax: Graph (4)	$\begin{aligned} & & (X_3 = 1.3)6.40 = 0.20 \\ \hline & & & & \\ \hline & & & & \\ \hline & & & & \\ & & & &$
Find the load factor $lpha_3$ of the dynamic moment.	C(3 = Me/Mea	A4 = 34 Meay = 6.40 (Same value as Meap)
Sum of the load factors		$\Omega_{S}^{\prime}$ = 1.8/6.4 = 0.28
Use is possible if the sum of the load factors does not exceed 1.	$\Sigma \alpha_n = \alpha_1 + \alpha_2 + \alpha_3 \leq 1$	$\sum \Omega n = \Omega_{1} + \Omega_{2} + \Omega_{2}' + \Omega_{3}' + \Omega_{3}'$ = 0.125 + 0.012 + 0.025 + 0.20 + 0.28 = 0.642 ≤ 1

### Model Selection **MXF** Series

Graph (1) Allowable Load Mass

1.0

0.7 0.5

0.4

0.3

0.2

1.0 >

> 0.7 0.5

> 0.4

0.3 02 50

Allowable Moment Coefficient:

50

100

100

200 300

Average operating speed Va (mm/s) Collision speed V (mm/s) Note) Use the average operating speed when calculating static moment.

Use the collision speed when calculating dynamic moment.

Graph (2) Allowable Moment Coefficient: 7

300

200 Average operating speed Va (mm/s)

500 700

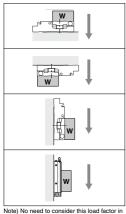
500 700

B

Allowable Load Mass Coefficient:

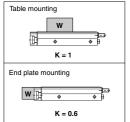
Coefficient: B

#### Fig. (1) Load Mass: W (kg)



the case of using perpendicularly in a vertical position.

#### Fig. (3) Workpiece Mounting Coefficient: K



#### Table (2) Maximum Allowable Load Mass: Wmax (kg)

Model	Maximum allowable load mass
MXF8	0.6
MXF12	1
MXF16	2
MXF20	4

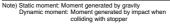
#### Fig. (2) Overhang: Ln (mm), Correction Values for Moment Center Distance: An (mm) Yaw moment Pitch moment Roll moment My ( -18 Mr ( -13 -11 • F w.L A٤ A<sub>1</sub> L. p. Static moment Аз Ŀ -8 Mr My ( -6 w.I w Aa A6 Lз A4 1 : Mey Мер Dynamic moment r h ٩ Å ¥

|MXQ 🗆 MXQ MXF MXW MXJ MXP MXY

MTS

MXH

MXS



#### Table (1) Maximum Allowable Kinetic Energy: Emax (J)

Model	Allowable kinetic energy
Model	Rubber bumper
MXF8	0.027
MXF12	0.055
MXF16	0.11
MXF20	0.16

#### Table (3) Moment Center Position Distance Compensation Amount: An (mm)

	Moment center position distance compensation amount (Refer to Fig. (2).)											
Model	<b>A</b> 1	A2	Аз	<b>A</b> 4	A5	A6						
MXF8	6 <sup>Note)</sup>	10	6 <sup>Note)</sup>	21	21	10						
MXF12	10	11	10	23	23	11						
MXF16	10	12	10	28	28	12						
MXF20	11	17	11	34	34	17						

Note) 16 mm for MXF8-10 only.

#### Table (4) Maximum Allowable Moment: Mmax (N·m)

Model	Stroke (mm)										
	10	20 30 50 75									
MXF8	0.56	0.78	0.98								
MXF12		1.65	2.22	3.34							
MXF16			3.41	5.69	7.96						
MXF20			6.66	9.14	13.70	18.27					

#### Symbol

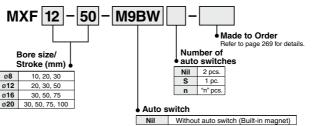
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Symbol	Definition	Unit	Symbol	Definition	Unit
An (n = 1 to 6)	Correction values of moment center position distance	mm	Va	Average operating speed	mm/s
E	Kinetic energy	J	w	Load mass	kg
Ea	Allowable kinetic energy	J	Wa	Allowable load mass	kg
Emax	Max. allowable kinetic energy	J	We	Mass equivalent to impact	kg
Ln (n = 1 to 3)	Overhang	mm	Wmax	Max. allowable load mass	kg
M (Mp, My, Mr)	Static moment (pitch, yaw, roll)	N∙m	α	Load factor	
Ma (Map, May, Mar)	Allowable static moment (pitch, yaw, roll)	N⋅m	β	Allowable load mass coefficient	
Me (Mep, Mey)	Dynamic moment (pitch, yaw)	N∙m	γ	Allowable moment coefficient	
Mea (Meap, Meay)	Allowable dynamic moment (pitch, yaw)	N∙m	δ	Damper coeficient	
Mmax (Mpmax, Mymax, Mrmax)	Maximum allowable moment (pitch, yaw, roll)	N⋅m	к	Workpiece mounting coefficient	
V	Collision speed	mm/s			



267

# Low Profile Slide Table

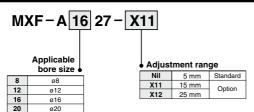
#### How to Order



\* For the applicable auto switch model, refer to the table below.

RoHS

#### How to Order Stroke Adjusting Bolt (Accessory)



\* -X12 (adjustable range 25 mm) is not available in the MXF8/MXF12 series.

#### Applicable Auto Switches/Refer to pages 1119 to 1245 for the detailed specifications of auto switches.

			light		L	oad volta	age	Auto swit	ch model	Lead	wire I	engtł	n (m)															
Туре		Special function Electrica entry		Indicator	Wiring (Output)	1	DC	AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)	5 (Z)	Pre-wired connector	Applio loa												
÷				3-wire (NPN)		5V.12V		M9NV	M9N	•	•	•	0	0	IC circuit													
switch				3-wire (PNP)		50,120		M9PV	M9P	•	•	•	0	0	IC CITCUIL													
sv				2-wire		12V		M9BV	M9B	٠	٠	٠	0	0	_													
auto	Diagnostic indication (2-color indicator) Grommet			3-wire (NPN)		Í		Í	5V.12V		M9NWV	M9NW	٠	•	•	0	0	IC circuit	<b>D</b> .1									
		or) Grommet Ye	Yes	3-wire (PNP)	24V	50,120	- [	- M9PWV	M9PW	0 0 0 C	0	0		Relay, PLC														
state				2-wire		12V		M9BWV	M9BW	٠	٠	٠	0	0	_	FLO												
			1	Water resistant													1	3-wire (NPN)	5V.12V		M9NAV*1	M9NA*1	0	0	•	0	0	IC circuit
Solid			(2-color indicator)					3-wire (PNP)		50,120		M9PAV*1	M9PA*1	0	0	٠	0	0	IC CIrcuit									
ő				2-wire		12V		M9BAV*1	M9BA*1	0	0	٠	0	0	_													
Reed auto switch		Yes	3-wire (Equiv. to NPN)	-	5V	-	A96V	A96	٠	-	•	-	-	IC circuit	—													
to s		Grommet		2-wire	24V	12V 100V	A93V*2	A93	٠	•	٠	•	-	-	Relay,													
au			None	2-wire	240	120	100V or less	A90V	A90	۰	—	۲	-	-	IC circuit	PLC												

\*1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.

\*2 1 m type lead wire is only applicable to D-A93.

\* Lead wire length symbols: 0.5 m ..... Nil (Example) M9NW

\* Solid state auto switches marked with " " are produced upon receipt of order.

1 m ...... M (Example) M9NWM 3 m ..... L (Example) M9NWL

5 m ······Z (Example) M9NWZ

\* Since there are other applicable auto switches than listed, refer to page 277 for details.

\* For details about auto switches with pre-wired connector, refer to pages 1192 and 1193

\* Auto switches are shipped together (not assembled).







Bore size (mm)	8	12	16	20					
Piping port size	M3 x 0.5		M5 x 0.8						
Fluid		A	ir						
Action		Double	acting						
Operating pressure		0.15 to 0	).7 MPa						
Proof pressure		1.05	MPa						
Ambient and fluid temperature	-10 to 60 °C								
Operating speed range (Average operating speed) Note)	50 to 500 mm/s								
Cushion		Rubber bumpe	r on both sides						
Lubrication		Non-	lube						
Auto switch (Option)	Reed auto switch Solid state auto switch (2-wire, 3-wire) 2-color indicator solid state auto switch (2-wire, 3-wire)								
Stroke length tolerance		+1 0 m	m						
Stroke adjustment range	Extension end 5 mm/Retraction end 5 mm								
Note) Average operating speed: Speed t	hat the stroke is	divided by a p	eriod of time fr	om starting the					

Note) Average operating speed: Speed that the stroke is divided by a period of time from starting th operation to reaching the end.

	Theoretica	al Output									
	Bore size	Rod size	Operating	Piston area		Opera	ating pr	essure	(MPa)		
	(mm)	(mm)	direction	(mm²)	0.2	0.3	0.4	0.5	0.6	0.7	
	8	4	OUT	50	10	15	20	25	30	35	
	0	4	IN	38	8	11	15	19	23	27	
	12	C C	OUT	113	23	34	45	57	68	79	
	12	6	IN	85	17	26	34	43	51	60	
	16	8	OUT	201	40	60	80	101	121	141	
	10	0	IN	151	30	45	60	76	91	106	
)		10	OUT	314	63	94	126	157	188	220	
	20	10	IN	236	47	71	94	118	142	165	

### Made to Order: Individual Specifications (For details, refer to pages 278 and 279.)

Symbol	Specifications
-X7	PTFE grease
-X9	Grease for food processing machines
-X11	Adjusting bolt, long specification (Adjustment range: 15 mm)
-X33	Without built-in auto switch magnet
-X39	Fluororubber seal
-X42	Anti-corrosive specifications for guide unit
-X45	EPDM seal

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm<sup>2</sup>)

#### Standard Stroke

Model	Standard stroke (mm)
MXF8	10, 20, 30
MXF12	20, 30, 50
MXF16	30, 50,7 5
MXF20	30, 50, 75, 100

#### Weight

						(9)								
Model	Standard stroke (mm)													
woder	10	20	30	50	75	100								
MXF8	120	130	170	_	_	_								
MXF12	_	210	250	360										
MXF16	_	_	360	500	690									
MXF20	_	_	600	750	1060	1370								

#### Moisture Control Tube IDK Series

Made to Order

When operating an actuator with a small diameter and a short stroke at a high frequency, the dew condensation (water droplet) may occur inside the piping depending on the conditions. Simply connecting the moisture control tube to the actuator will prevent dew condensation from occurring. For details, refer to <u>the IDK se-</u> <u>rise in the Best Pneumatics No. 6.</u>



MXH MXS MXQ MXQ MXF MXW MXJ

MXP MXY MTS

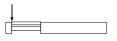
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(a)

#### Table Deflection (Reference Values)

### Table displacement due to pitch moment load

Table displacement when loads are applied to the section marked with the arrow at the full stroke.



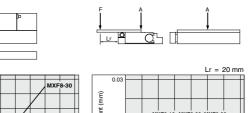
#### Table displacement due to yaw moment load

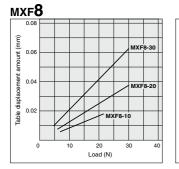
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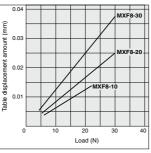
Table displacement when loads are applied to the section marked with the arrow at the full stroke.

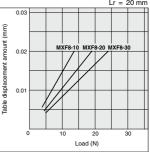
### Table displacement due to roll moment load

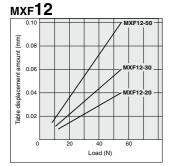
Table displacement of section A when loads are applied to the section F with the slide table retracted.

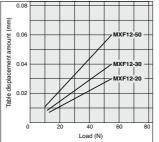


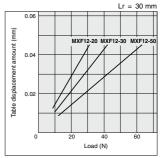












### Low Profile Slide Table **MXF** Series

The graphs below show the table displacement when the static moment load is applied to the table. The graphs do not show the loadable mass. Refer to the Model Selection for the loadable mass.

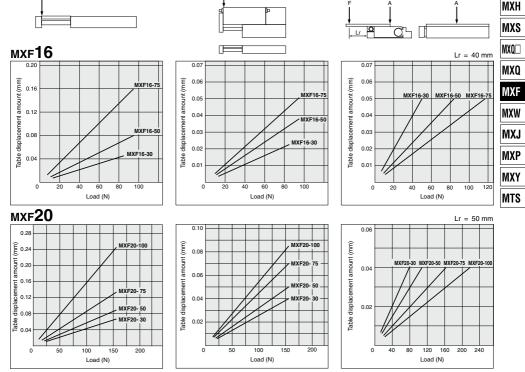
Table displacement due to

#### Table displacement due to pitch moment load

#### Table displacement when loads are applied to the section marked with the arrow at the full stroke.

#### Table displacement due to yaw moment load

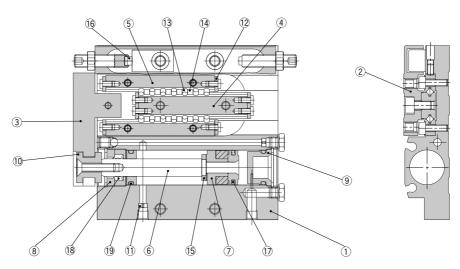
Table displacement when loads are applied to the section marked with the arrow at the full stroke. roll moment load Table displacement of section A when loads are applied to the section F with the slide table retracted.



D-□ -X□

### **MXF** Series

#### Construction



#### **Component Parts**

No.	Description	Material	Note
1	Body	Aluminum alloy	Hard anodized
2	Table	Aluminum alloy	Hard anodized
3	End plate	Aluminum alloy	Hard anodized
4	Rail	Carbon tool steel	Heat treated
5	Guide	Carbon tool steel	Heat treated
6	Rod	Stainless steel	
7	Piston assembly	—	With magnet
8	Seal support	Brass	Electroless nickel plated
9	Head cap	Resin	
10	Floating bushing	Stainless steel	
11	Orifice	Brass	Electroless nickel plated
12	Roller stopper	Stainless steel	
13	Cylindrical roller	High carbon chrome bearing steel	
14	Roller spacer	Resin	
15	Rod bumper	Polyurethane	

#### **Component Parts**

No.	Description	Material	Note
16	Adjust bumper	Polyurethane	
17	Piston seal	NBR	
18	Rod seal	NBR	
19	O-ring	NBR	

#### **Replacement Parts: Seal Kit**

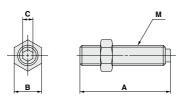
Bore size (mm)	Kit no.	Contents
8	MXF8-PS	
12	MXF12-PS	<b>1</b>
16	MXF16-PS	Set of nos. above 🗊 to 🗐
20	MXF20-PS	

\* Seal kit includes (1), (18, (19. Order the seal kit, based on each bore size.

#### **Replacement Part: Grease Pack**

Applied part	Grease pack part no.
Guide	GR-S-010 (10g) GR-S-020 (20g)
Cylinder	GR-L-005 (5g) GR-L-010 (10g)

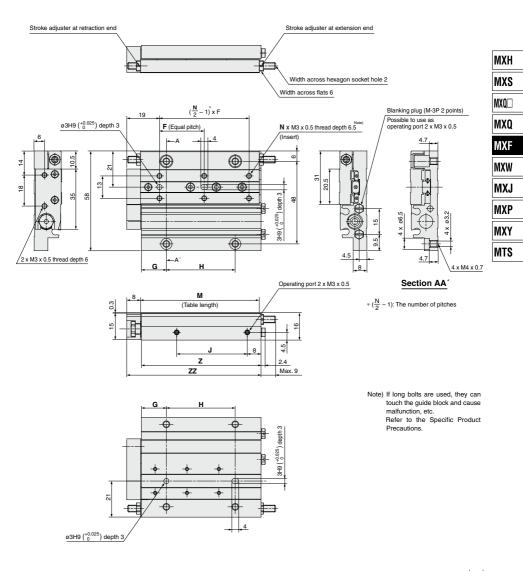
#### **Dimensions: Stroke Adjustment Bolt**



Applicable size	Model	Stroke adjustment range (mm)	A	в	с	м	
MXF8	MXF-A827	5	17	6	2	M4 x 0.7	
IVIAFO	MXF-A827-X11	15	27	0	-	WI4 X 0.7	
MXF12	MXF-A1227	5	23.5	7	2.5	M5 x 0.8	
WAF12	MXF-A1227-X11	15	33.5		2.5	IVIS X 0.0	
	MXF-A1627	5	26.5				
MXF16	MXF-A1627-X11	15	36.5	8	3	M6 x 1	
	MXF-A1627-X12	25	46.5				
	MXF-A2027	5	30				
MXF20	MXF-A2027-X11	15	40	12	4	M8 x 1	
	MXF-A2027-X12	25	50				

**SMC** 

Dimensions: MXF

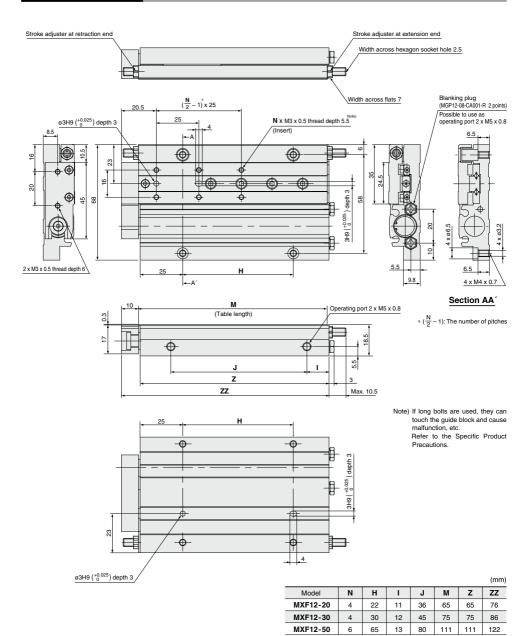


								(mm)
Model	F	N	G	н	J	М	Z	ZZ
MXF8-10	20	4	13.5	22	21	49	49.5	58
MXF8-20	26	4	14.5	26	26	54	54.5	63
MXF8-30	26	6	14.5	40	41	69	69.5	78

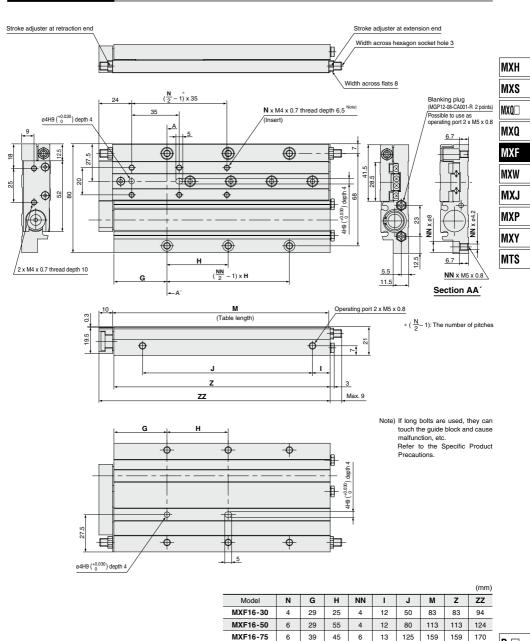
D-□ -X□

### **MXF** Series

### Dimensions: MXF 12



#### **Dimensions: MXF16**

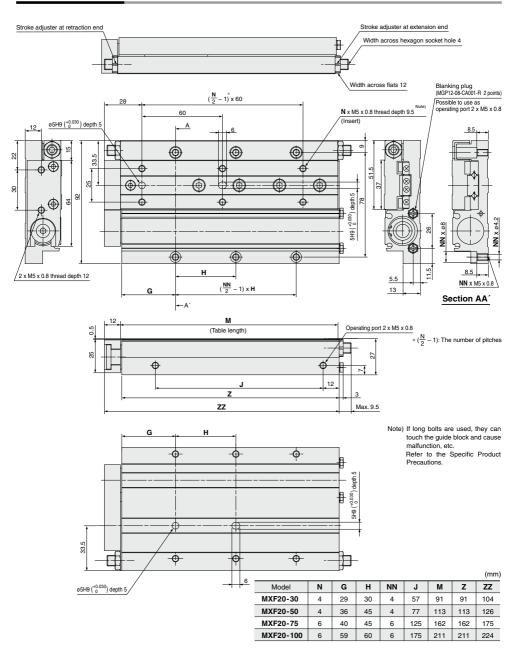


D-🗆 -X□

6 39 45 6 13 125 159 159 170

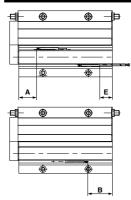
### **MXF** Series

#### **Dimensions: MXF20**



# **MXF** Series **Auto Switch Mounting**

#### Auto Switch Proper Mounting Position (Detection at Stroke End)



Reed Auto Sw	eed Auto Switch: D-A90, D-A93, D-A96, D-A90V, D-A93V, D-A96V (mm														
				В				E							
Model	A			Stro	ke			Stroke							
		10	20	30	50	75	100	10	20	30	50	75	100		
MXF8	9.5	10	5	10	-	—	_	8 (5.5)	3 (0.5)	8 (5.5)	-	-	—		
MXF12	12	—	13.1	13.1	29.1	—	-	—	11.1 (8.6)	11.1 (8.6)	27.1 (24.6)	-	—		
MXF16	17.2	—	—	15.8	25.8	46.8	_	—	—	13.8 (11.3)	23.8 (21.3)	44.8 (42.3)	—		
MXF20	19.4	_	_	20.7	22.7	46.2	70.7	_	_	18.7	20.7	44.2	68.7		

#### Solid State Auto Switch: D-M9B, D-M9N, D-M9P, D-M9BW, D-M9NW, D-M9PW, D-M9DA (mm)

		В					E					E (D-M9□A)						MXW		
Model	A		Stroke							Str	oke					Str	oke			
		10	20	30	50	75	100	10	20	30	50	75	100	10	20	30	50	75	100	MXJ
MXF8	13.5	14	9	14	—	—	—	4	-1	4	-	-	-	2	-3	2	-	-	—	МХР
MXF12	16	—	17.1	17.1	33.1	-	-	_	7.1	7.1	23.1	-	-	-	5.1	5.1	21.1	-	—	INIVL
MXF16	21.2	—	—	19.8	29.8	50.8	—	—	-	9.8	19.8	40.8	-	_	—	7.8	17.8	38.8	—	MXY
MXF20	23.4	-	_	24.7	26.7	50.2	74.7	_	_	14.7	16.7	40.2	64.7	_	-	12.7	14.7	38.2	62.7	III/(I

MTS

MXH MXS MXO

MXQ

MXF

#### Solid State Auto Switch: D-M9BV, D-M9NV, D-M9PV, D-M9BWV, D-M9NWV, D-M9PWV, D-M9QAV (mm)

					,			,			-,-		,			.,		(		
		В								E				E (D-M9□AV)						
Model A	A	Stroke							Stroke						Stroke					
		10	20	30	50	75	100	10	20	30	50	75	100	10	20	30	50	75	100	
MXF8	13.5	14	9	14	_	-	-	6	1	6	_	-	-	4	-1	4	-	-	—	
MXF12	16	_	17.1	17.1	33.1	-	-	-	9.1	9.1	25.1	-	-	-	7.1	7.1	23.1	-	—	
MXF16	21.2	_	-	19.8	29.8	50.8	-	-	_	11.8	21.8	42.3	-	-	_	9.8	19.8	40.3	—	
MXF20	23.4	_	_	24.7	26.7	50.2	74.7	_	_	16.7	18.7	42.2	66.7	_	_	14.7	16.7	40.2	64.7	

\* ( ): Denotes the values of D-A93. Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

### Auto Switch Mounting

Auto switch mounting screw (included with auto switch) Watchmaker's screwdrive

/Auto switch

#### Auto Switch Mounting Tool

Caution Auto Switch included with auto switch), use a watchmaker's screwdriver with a handle about 5 to 6 mm in diameter.

#### **Tiahtenina Toraue**

#### Tightening Torque of Auto Switch Mounting Screw (N.m)

ingitioning rendue et state entitet meaning eeten (it m			
Auto switch model	Tightening torque		
D-A9□(V)	0.10 to 0.20		
D-M9□(V)	0.05 + 0.45		
D-M9□W(V) D-M9□A, M9□AV	0.05 to 0.15		

### **Operating Range**

Auto switch model	Applicable bore size (mm)			
	8	12	16	20
D-A9□(V)	4.5	5	6	7
D-M9□, M9□V D-M9□W, M9□WV D-M9□A, M9□AV	3	3	4.5	5

\* Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.

Other than the models listed in "How to Order", the following auto switches are applicable.

\* Normally closed (NC = b contact) solid state auto switches (D-F9G/F9H types) and solid state auto switch D-F8 are also available.

For details, refer to pages 1136 and 1137.



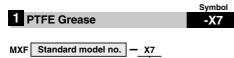


D-I

### *MXF series* Made to Order: Individual Specifications 1



Please contact SMC for detailed dimensions, specifications and lead times.



• PTFE grease

PTFE grease is used for all parts that grease is applied.

#### Specifications

 Type
 PTFE grease

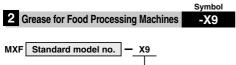
 Bore size (mm)
 8, 12, 16, 20

\* Dimensions other than the above is the same as the standard type.

#### A Warning

#### Precautions

Be aware that smoking cigarettes, etc. after your hands have come into contact with the grease used in this cylinder can create a gas that is hazardous to humans.



 Grease for food processing machines

Grease for food processing machines is used for all parts that grease is applied.

#### Specifications

Туре	Grease for food processing machines (NSF-H1 certified)/Aluminum complex soap base grease	
Bore size (mm)	8, 12, 16, 20	

\* Dimensions other than the above is the same as the standard type.

# Caution Do not use this cylinder in a food-related environment. Solish zore

<Cannot be mounted> Food zone---Food may directly contact with this cylinder, and is treated as food products.

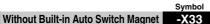
Non-food zone...This cylinder do not directly

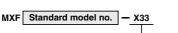
cylinder, and is treated as food products. <Can be mounted> Splash zone--Food may directly contact with this cylinder, but is not treated as food



Food zone

Cannot be mounted





Without built-in auto switch magnet

Auto switch magnet is not built in.

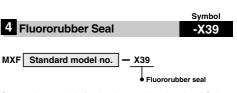
#### Specifications

products

contact food.

Туре	Without built-in auto switch magnet	
Bore size (mm)	8, 12, 16, 20	
Auto switch	Not mountable	

\* Dimensions other than the above is the same as the standard type

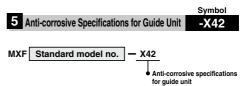


Change the materials for the piston seal, rod seal and O-rings to fluororubber.

#### Specifications

Type Fluororubber seal	
Bore size (mm)	8, 12, 16, 20
Seal material	Fluororubber

\* Dimensions other than the above is the same as the standard type.



Rail and guide are given anti-corrosive treatment.

#### Specifications

Туре	Anti-corrosive guide unit	
Bore size (mm)	8, 12, 16, 20	
Surface treatment Special anti-corrosive treatment		

\* 1 Dimensions other than the above is the same as the standard type.

\* 2 Special anti-corrosive treatment makes the rail and the guide black.



#### MXF Standard model no. - X45

EPDM seal

Change the materials for the piston seal, rod seal and O-rings to EPDM.

#### Specifications

Туре	EPDM seal	
Bore size (mm)	8, 12, 16, 20	
Seal material	EPDM	
Grease	PTFE grease	

\* Dimensions other than the above is the same as the standard type.

### Marning Precautions

@SMC

Be aware that smoking cigarettes, etc. after your hands have come into contact with the grease used in this cylinder can create a gas that is hazardous to humans.

MXF Series Made to Order: Individual Specifications 2 Please contact SMC for detailed dimensions, specifications and lead times.

7 Adjusting Bolt, Long Specification (Adjustment range: 15 mm)		Sym -X		
MXF Standard model no. — X11				MXH
Adjusting bolt, long specification				MXS
(Adjustment range: 15 mm)				MXQ
The average adjusting stroke range was extended from 5 mm to 15 mm with a long adjusting bolt.				MXO
Dimensions				MX
For backward-facing end For forward-facing end				MXV
				-
				MX
				MX
				MX
				MT
			(mm)	
	Model	A	В	
	MXF8 MXF12	10 10	19 20.5	
	MXF12 MXF16	10	20.5	
	MXF20	10	19.5	



### MXF Series Specific Product Precautions

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

Mounting

#### Mounting of Body

**A** Caution

- Do not scratch or dent the mounting side of the body, table or end plate. It causes play in the guide section and increases sliding resistance.
- Do not scratch or dent on the forward side of the rail or guide. It will result in looseness of the guide section and increased sliding resistance.
- Keep away from objects which are influenced by magnets.

As the piston part has magnets built-in, do not allow close contact with magnetic disks, magnetic cards or magnetic tapes. Data may be erased.

- 4. When mounting the body, use screws with appropriate length and do not exceed the maximum tightening torque. Tightening with a torque above the limit could malfunction. Whereas tightening insufficiently could result in misalignment or come to a drop.
- Be careful when adjusting stroke not to allow cylinder end plate to bottom out against cylinder body.

#### Positioning

### **▲** Caution

 The positioning hole on the table and on the bottom of the body does not have the same center. Positioning hole is meant to be for reproducibility for mounting and dismounting.



### ▲ Caution

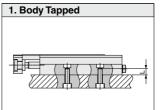
1. If intermediate stop by external stopper is done, avoid ejection.

If ejection occurs, it may cause damage. In the case the slide table is stopped at an intermediate position by an external stopper then forwarded to the front, return the slide table to the back for just a moment to retract the stopper, then supply pressure to the opposite port to operate slide table.

2. Do not use it in such a way that excessive external force or impact force could work on it.

This could result in damage.

The slide table can be mounted from 2 directions. Select the best direction according to your application.



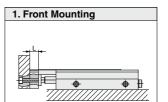
Model	Bolt	Maximum tightening torque (N·m)	Maximum screw-in depth L (mm)
MXF8	M4 x 0.7	2.1	4.7
MXF12	M4 x 0.7	2.1	6.5
MXF16	M5 x 0.8	4.4	6.7
MXF20	M5 x 0.8	4.4	8.5

2. Bo	2. Body Through-hole				
Model	Bolt	Maximum tightening torque (N·m)	Maximum screw-in depth L (mm)		
MXF8	M3 x 0.5	1.2	4.7		

Model	Bolt	tightening torque (N·m)	Maximum screw-in depth L (mm)
MXF8	M3 x 0.5	1.2	4.7
MXF12	M3 x 0.5	1.2	6.5
MXF16	M4 x 0.7	2.8	6.7
MXF20	M4 x 0.7	2.8	8.5

▲ Caution 0.02 mm or less of flatness is recommended for the body mounting surface. An uneven mounting surface of a workpiece or a base may cause vibration or increase sliding resistance.

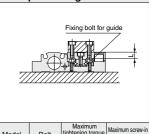
#### Mounting of Workpiece



Work can be mounted on two sides of the body.

Model	Bolt	Maximum tightening torque (N·m)	Maximum screw-in depth L (mm)
MXF8	M3 x 0.5	0.9	6
MXF12	M3 x 0.5	0.9	6
MXF16	M4 x 0.7	2.1	10
MXF20	M5 x 0.8	4.4	12

#### 2. Top Mounting



Model	Bolt	tightening torque (N·m)	Maximum screw-in depth L (mm)
MXF8	M3 x 0.5	0.9	6.5
MXF12	M3 x 0.5	0.9	5.5
MXF16	M4 x 0.7	2.1	6.5
MXF20	M5 x 0.8	4.4	9.5

### **A** Caution

To prevent the workpiece holding bolts from touching the guide holding bolts, use bolts that are 0.5 mm or more shorter than the maximum screw-in depth.

If the bolts are too long, they hit the end plate and may cause malfunctions.